

6.5 Least squares problems

$\swarrow m \times n$
 $A\vec{x} = \vec{b}$ (possibly inconsistent)

Find $\hat{\vec{x}}$ that minimizes $\|\vec{b} - A\vec{x}\|$

\uparrow a "least squares solution" to $A\vec{x} = \vec{b}$

$$W = \text{Col } A$$

$$\hat{\vec{b}} = \text{proj}_W \vec{b}$$

Then $\|\vec{b} - \hat{\vec{b}}\| \leq \|\vec{b} - \vec{v}\|$ for all $\vec{v} \in W$

But $\vec{x} \in \mathbb{R}^n \Rightarrow \vec{v} = A\vec{x} \in \text{Col } A = W$

So $\|\vec{b} - \hat{\vec{b}}\| \leq \|\vec{b} - A\vec{x}\|$ for all $\vec{x} \in \mathbb{R}^n$

Can we find $\hat{\vec{x}}$ such that $\hat{\vec{b}} = A\hat{\vec{x}}$?

YES! Because $\hat{\vec{b}} \in W = \text{Col } A$.

So there does exist such an $\hat{\vec{x}}$.

How do we find it?

$$\vec{b} - \hat{\vec{b}} \in W^\perp$$

Write $A = (\vec{a}_1 \cdots \vec{a}_n)$

Each $\vec{a}_j \in W$. Therefore ...

$$\vec{a}_j \cdot (\vec{b} - \hat{\vec{b}}) = 0 \quad \text{for all } j$$

$$\vec{a}_j^T (\vec{b} - A \hat{\vec{x}}) = 0 \quad \text{for all } j$$

$$\begin{pmatrix} \vec{a}_1^T \\ \vdots \\ \vec{a}_n^T \end{pmatrix} (\vec{b} - A \hat{\vec{x}}) = \vec{0}$$

$$A^T (\vec{b} - A \hat{\vec{x}}) = \vec{0}$$

$$A^T \vec{b} - A^T A \hat{\vec{x}} = \vec{0}$$

$$A^T A \hat{\vec{x}} = A^T \vec{b}$$

Find $\hat{\vec{x}}$ by solving

consistent

$$A^T A \vec{x} = A^T \vec{b}$$

called the
"normal equations"
for $A \vec{x} = \vec{b}$

Thm 13

The set of least-squares solns to $A \vec{x} = \vec{b}$ is
the soln set to $A^T A \vec{x} = A^T \vec{b}$, which is nonempty.

Expl 1

$$A = \begin{pmatrix} 4 & 0 \\ 0 & 2 \\ 1 & 1 \end{pmatrix}, \quad \vec{b} = \begin{pmatrix} 2 \\ 0 \\ 11 \end{pmatrix}$$

$A\vec{x} = \vec{b}$ is inconsistent. Find a least-squares soln to $A\vec{x} = \vec{b}$.

$$A^T A = \begin{pmatrix} 4 & 0 & 1 \\ 0 & 2 & 1 \end{pmatrix} \begin{pmatrix} 4 & 0 \\ 0 & 2 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 17 & 1 \\ 1 & 5 \end{pmatrix}$$

$$A^T \vec{b} = \begin{pmatrix} 4 & 0 & 1 \\ 0 & 2 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 0 \\ 11 \end{pmatrix} = \begin{pmatrix} 19 \\ 11 \end{pmatrix}$$

$$\begin{pmatrix} 17 & 1 \\ 1 & 5 \end{pmatrix} \vec{x} = \begin{pmatrix} 19 \\ 11 \end{pmatrix}$$

$$\begin{pmatrix} 17 & 1 \\ 1 & 5 \end{pmatrix}^{-1} = \frac{1}{85-1} \begin{pmatrix} 5 & -1 \\ -1 & 17 \end{pmatrix}$$

$$\vec{x} = \frac{1}{84} \begin{pmatrix} 5 & -1 \\ -1 & 17 \end{pmatrix} \begin{pmatrix} 19 \\ 11 \end{pmatrix} = \frac{1}{84} \begin{pmatrix} 95 - 11 \\ -19 + 187 \end{pmatrix}$$

$$= \frac{1}{84} \begin{pmatrix} 84 \\ 168 \end{pmatrix} = \boxed{\begin{pmatrix} 1 \\ 2 \end{pmatrix}}$$

Thm 14

Let A be $m \times n$. TFAE:

(a) $A\hat{x} = b$ has a unique least-squares soln for each $b \in \mathbb{R}^m$.

(b) The cols of A are lin. indep.

(c) $A^T A$ is invertible.

In these cases, $\hat{x} = (A^T A)^{-1} A^T b$.

$\|b - A\hat{x}\|$ is called the least-squares error.

Expl 3

What is the least squares error in Expl 1?

$$b = \begin{pmatrix} 2 \\ 0 \\ 11 \end{pmatrix}, \quad \hat{x} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$A\hat{x} = \begin{pmatrix} 4 & 0 \\ 0 & 2 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 4 \\ 4 \\ 3 \end{pmatrix}$$

$$\|b - A\hat{x}\|^2 = \left\| \begin{pmatrix} -2 \\ -4 \\ 8 \end{pmatrix} \right\|^2 = 4 + 16 + 64 = 84$$

$$\|b - A\hat{x}\| = \sqrt{84} = \boxed{2\sqrt{21}}$$

Expt 4

$$A = \begin{pmatrix} 1 & -6 \\ 1 & -2 \\ 1 & 1 \\ 1 & 7 \end{pmatrix}, \quad \vec{b} = \begin{pmatrix} -1 \\ 2 \\ 1 \\ 6 \end{pmatrix}. \quad \text{Find a least-squares soln to } A\vec{x} = \vec{b}.$$

\vec{a}_1 \vec{a}_2
or orthogonal

$$\hat{\vec{b}} = \text{proj}_{\text{Col}A} \vec{b} \rightarrow \text{Span}\{\vec{a}_1, \vec{a}_2\}$$

$$= \frac{\vec{b} \cdot \vec{a}_1}{\vec{a}_1 \cdot \vec{a}_1} \vec{a}_1 + \frac{\vec{b} \cdot \vec{a}_2}{\vec{a}_2 \cdot \vec{a}_2} \vec{a}_2$$

$$= \frac{-1+2+1+6}{1+1+1+1} \vec{a}_1 + \frac{6-4+1+42}{36+4+1+49} \vec{a}_2$$

$$= 2\vec{a}_1 + \frac{45}{90} \vec{a}_2 = 2\vec{a}_1 + \frac{1}{2} \vec{a}_2$$

Solve $A\vec{x} = \hat{\vec{b}}$

$$(\vec{a}_1 \ \vec{a}_2) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 2\vec{a}_1 + \frac{1}{2} \vec{a}_2$$

$$x_1 \vec{a}_1 + x_2 \vec{a}_2 = 2\vec{a}_1 + \frac{1}{2} \vec{a}_2 \Rightarrow \begin{matrix} x_1 = 2 \\ x_2 = \frac{1}{2} \end{matrix}$$

$$\hat{\vec{x}} = \begin{pmatrix} 2 \\ 1/2 \end{pmatrix}$$

Thm 15

A : $m \times n$, lin. indep. cols

$$A = QR \leftarrow \text{QR-factorization}$$

$m \times n$, cols are an
orthonormal basis
for $\text{Col } A$

$n \times n$, upper triangular,
positive entries on
the diagonal

Then $\hat{x} = R^{-1} Q^T b$

in practice, write $R \hat{x} = Q^T b$
and solve by row reduction

Expl 5

$$A = \begin{pmatrix} 1 & 3 & 5 \\ 1 & 1 & 0 \\ 1 & 1 & 2 \\ 1 & 3 & 3 \end{pmatrix}, \quad b = \begin{pmatrix} 3 \\ 5 \\ 7 \\ -3 \end{pmatrix}$$

Find a least-squares soln to $A\vec{x} = b$.

Find an orthonormal basis for $\text{Col } A$
(use Gram-Schmidt), then make $Q \dots$

$$Q = \frac{1}{2} \begin{pmatrix} 1 & 1 & 1 \\ 1 & -1 & -1 \\ 1 & -1 & 1 \\ 1 & 1 & -1 \end{pmatrix}$$

$$\text{Then } R = Q^T A = \overset{\text{calculate}}{\downarrow} \dots = \begin{pmatrix} 2 & 4 & 5 \\ 0 & 2 & 3 \\ 0 & 0 & 2 \end{pmatrix}$$

$$Q^T b = \overset{\text{calculate}}{\downarrow} \dots = \begin{pmatrix} 6 \\ -6 \\ 4 \end{pmatrix}$$

$$R \hat{x} = Q^T b \Rightarrow \begin{pmatrix} 2 & 4 & 5 \\ 0 & 2 & 3 \\ 0 & 0 & 2 \end{pmatrix} \hat{x} = \begin{pmatrix} 6 \\ -6 \\ 4 \end{pmatrix}$$

Solve ... (easy b/c R is upper triangular) ...

$$\boxed{\hat{x} = \begin{pmatrix} 10 \\ -6 \\ 2 \end{pmatrix}}$$