

Large deviations and a non-Markovian vanishing viscosity result

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1 Introduction

2 BSDEs

- A simple BSDE and the Feynman-Kac formula
- Nonlinear BSDEs and stochastic optimal control
- Quadratic and super-quadratic BSDEs

3 Path-dependent calculus and path-dependent PDEs

- PPDEs
- Motivation
- Path derivatives
- Viscosity solutions

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Setting:

- $\Omega = C([0, T], \mathbb{R}^d)$ with $d = 1$ (for simplicity)
- P probability on $\mathcal{B}(\Omega)$
- $W = (W_t)_{0 \leq t \leq T}$ standard P -Wiener process on Ω
- $\mathbb{F} = \mathbb{F}^W$

Schilder's theorem in Laplace form

(see, e.g., Dupuis–Ellis (97), Boué–Dupuis (AOP, 98)). For every $h \in C_b(\Omega)$,

$$\lim_{n \rightarrow \infty} -\frac{1}{n} \log E \left[e^{-nh(W/\sqrt{n})} \right] = \inf_{x \in AC([0, T]) \text{ with } x(0) = 0} \left\{ \int_0^T |x'(t)|^2 dt + h(x) \right\}.$$

Non-exponential Schilder theorem in Laplace form

(Backhoff-Veraguas–Lacker–Tangpi (AAP, 2020)). For every $h \in C_b(\Omega)$,

$$\lim_{n \rightarrow \infty} -\rho^{-\ell_n} [-h(W/\sqrt{n})] = \inf_{x \in AC([0, T]) \text{ with } x(0) = 0} \left\{ \int_0^T \ell(t, x'(t)) dt + h(x) \right\}.$$

Here, $\ell_n(t, a) = \ell(t, a/\sqrt{n})$. (The operator $\rho^{-\ell_n}$ will be defined later.)

Applications of “large deviations” results and open problem

(Backhoff-Veraguas–Lacker–Tangpi (AAP, 2020))

Assume ℓ is coercive, i.e., $\lim_{|a| \rightarrow \infty} \frac{\ell(t, a)}{|a|} = \infty$.

- **General (non-Markovian) case:**

“Solutions” of **BSDEs** converge to value function of a calculus-of-variations problem with path-dependent terminal cost $h : \Omega \rightarrow \mathbb{R}$.

- **Markovian case:** Say $h(\omega) = \tilde{h}(\omega_T)$.

Vanishing viscosity result:

“Solutions” u_n of (possibly super-quadratic) HJB equation

$$\partial_t u_n + \frac{1}{2n} \partial_{xx} u_n + \inf_{a \in \mathbb{R}} [\ell(t, a) + a \cdot \partial_x u_n] = 0 \quad \text{on } (0, T) \times \mathbb{R}$$

$$u_n(T, x) = \tilde{h}(x) \quad \text{on } \mathbb{R},$$

converge pointwise to value function u of a calculus-of-variations problem and “formally”

$$\partial_t u + \inf_{a \in \mathbb{R}} [\ell(t, a) + a \cdot \partial_x u] = 0 \quad \text{on } (0, T) \times \mathbb{R}$$

$$u(T, x) = \tilde{h}(x) \quad \text{on } \mathbb{R}.$$

Open problem: Is there a **non-Markovian vanishing viscosity result** in terms of **(path-dependent) PDEs** on $[0, T] \times \Omega$? (Recall that $\Omega = C([0, T])$.)

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Fix (bounded) \mathcal{F}_T -measurable random variable $h : \Omega \rightarrow \mathbb{R}$, i.e., $h = h(W)$.

- 1st try: Find a process $Y = (Y_t)_{0 \leq t \leq T}$ such that

$$dY_t = 0 \cdot dt \quad \text{on } [0, T], \quad Y_T = h.$$

Then $Y_t = h$, $t \in [0, T]$. Problem: Y is not \mathbb{F} -adapted.

- 2nd try: Possibly more useful solution would be $Y_t := E[h|\mathcal{F}_t]$. In this case,

$$\boxed{dY_t = Z_t dW_t} \quad \text{on } [0, T], \quad Y_T = h, \quad (1)$$

for some process Z .

Solution of BSDE (1) is a pair (Y, Z) of \mathbb{F} -progressive processes.

Interpretation from financial math point of view:

- W "price" process of underlying asset
- h contingent claim/ derivative
- Y price process of contingent claim
- Z replicating/ hedging strategy

Consider the BSDE

$$dY_t = Z_t dW_t \quad \text{on } [0, T], \quad Y_T = \tilde{h}(W_T). \quad (2)$$

Assume that there is a $u \in C^{1,2}([0, T] \times \mathbb{R})$ such that

$$Y_t = u(t, W_t) \quad \text{for all } t \in [0, T].$$

Then, from

$$\begin{aligned} du(t, W_t) &= \left[\partial_t + \frac{1}{2} \partial_{xx} \right] u(t, W_t) dt + \partial_x u(t, W_t) dW_t, \\ dY_t &= 0 dt + Z_t dW_t, \end{aligned}$$

one can deduce that $Z_t = \partial_x u(t, W_t)$ and that u solves the heat equation

$$\begin{aligned} \left[\partial_t + \frac{1}{2} \partial_{xx} \right] u(t, x) &= 0 \quad \text{on } (0, T) \times \mathbb{R}, \\ u(T, x) &= \tilde{h}(x) \quad \text{on } \mathbb{R}. \end{aligned} \quad (3)$$

Vice versa: If u solves (3), then $(Y, Z) := (u(t, W_t), \partial_x u(t, W_t))_{0 \leq t \leq T}$ solves (2).

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Theorem (Pardoux–Peng (90), see also Zhang (2017))

Let $h \in L^2(\mathcal{F}_T, P)$ and let $f = f(t, y, z) : [0, T] \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ be Borel with $f(\cdot, 0, 0) \in L^1$ and assume that there is an $L > 0$ such that, for all $t \in [0, T]$, $y, \tilde{y}, z, \tilde{z} \in \mathbb{R}$,

$$|f(t, y, z) - f(t, \tilde{y}, \tilde{z})| \leq L(|y - \tilde{y}| + |z - \tilde{z}|).$$

Then the BSDE

$$dY_t = -f(t, Y_t, Z_t) dt + Z_t dW_t \quad \text{on } [0, T], \quad Y_T = h, \quad (4)$$

has a unique solution $(Y, Z) \in \mathbb{L}^2(\mathbb{F}) \times \mathbb{L}^2(\mathbb{F})$.

Theorem (Peng (91), see also Ma–Yong (99))

Let $u \in C^{1,2}([0, T] \times \mathbb{R})$ solve

$$\begin{aligned} \left[\partial_t + \frac{1}{2} \partial_{xx} \right] u(t, x) + f(t, u(t, x), \partial_x u(t, x)) &= 0 && \text{on } (0, T) \times \mathbb{R}, \\ u(T, x) &= \tilde{h}(x) && \text{on } \mathbb{R}. \end{aligned} \quad (5)$$

Then $(Y, Z) := (u(t, W_t), \partial_x u(t, W_t))_{0 \leq t \leq T}$ solves (4) with $h := \tilde{h}(W_T)$.

Let $\ell : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ and $\tilde{h} : \mathbb{R} \rightarrow \mathbb{R}$ be bounded and Borel.

Fix $m > 0$. Given $(t, x) \in [0, T] \times \mathbb{R}$, minimize

$$J(t, x, a(\cdot)) := E \left[\int_t^T \ell(s, a(s)) ds + \tilde{h} \left(X_T^{t,x,a(\cdot)} \right) \right]$$

over all $a(\cdot) : [0, T] \times \Omega \rightarrow [-m, m]$ that are \mathbb{F} -progressive subject to

$$dX_s^{t,x,a(\cdot)} = a(s) ds + dW_s \quad \text{on } [t, T], \quad X_t^{t,x} = x.$$

The value function $V : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ is defined by

$$V(t, x) := \inf_{a(\cdot)} J(t, x, a(\cdot)).$$

BSDE connection: Assume that $V \in C^{1,2}$. Then V solves HJB equation

$$\left[\partial_t + \frac{1}{2} \partial_{xx} \right] V(t, x) + \inf_{|a| \leq m} [\ell(t, a) + a \cdot \partial_x V(t, x)] = 0, \quad \text{on } (0, T) \times \mathbb{R},$$

$$V(T, x) = \tilde{h}(x) \quad \text{on } \mathbb{R}.$$

Moreover, by nonlinear Feynman-Kac, $(Y, Z) = (V(t, W_t), \partial_x V(t, W_t))_{0 \leq t \leq T}$ solves

$$dY_t = - \inf_{|a| \leq m} [\ell(t, a) + a \cdot Z_t] dt + Z_t dW_t \quad \text{on } [0, T], \quad Y_T = \tilde{h}(W_T).$$

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Quadratic and super-quadratic BSDEs

Consider BSDE

$$dY_t = -f(t, Y_t, Z_t) dt + Z_t dW_t \quad \text{on } [0, T], \quad Y_T = h. \quad (6)$$

Quadratic BSDE: $|f(t, y, z)| \leq C(1 + |z|^2)$

Well-posedness of solutions (Kobylanski, AOP, 2000)

Super-quadratic BSDE: $\lim_{|z| \rightarrow \infty} \frac{|f(t, y, z)|}{|z|^2} = \infty$

- Ill-posedness of solutions (Delbaen–Hu–Bao, PTRF, 2011)
- Well-posedness of minimal supersolutions (Drapeau–Heyne–Kupper, AOP, 2013)

$(Y, Z) \in \mathbb{L}^2(\mathbb{F}) \times \mathbb{L}^2(\mathbb{F})$ supersolution of (6) if Y is càdlàg, $\int Z dW$ a supermartingale,

- $Y_s \geq Y_t + \int_t^s [-f(r, Y_r, Z_r)] dr + \int_t^s Z_r dW_r$, and
- $Y_T \geq h$.

(Y, Z) minimal supersolution of (6) if

- (\tilde{Y}, \tilde{Z}) supersolution of (6) $\implies Y \leq \tilde{Y}$.

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PPDE

$$\begin{aligned} -\partial_t u - F(t, \omega, u, \partial_\omega u, \partial_{\omega\omega}^2 u) &= 0 && \text{on } [0, T) \times \Omega, \\ u(T, \omega) &= h(\omega) && \text{on } \Omega. \end{aligned}$$

- Ω path space:

$$C([0, T], \mathbb{R}^d), D([0, T], \mathbb{R}^d), C([0, T], H), \dots$$

- $F = F(t, \omega, y, z, \gamma)$ Hamiltonian
- $u = u(t, \omega) : [0, T] \times \Omega \rightarrow \mathbb{R}$ *non-anticipating*, i.e.,

$$u(t, \omega) = u(t, \omega_{\cdot \wedge t}) \quad \text{"="} \quad u(t, \{\omega_s\}_{s \leq t})$$

PPDE

$$\begin{aligned} -\partial_t u - F(t, \omega, u, \partial_\omega u, \partial_{\omega\omega}^2 u) &= 0 && \text{on } [0, T) \times \Omega, \\ u(T, \omega) &= h(\omega) && \text{on } \Omega. \end{aligned}$$

- Ω path space:

$$C([0, T], \mathbb{R}^d), D([0, T], \mathbb{R}^d), C([0, T], H), \dots$$

- $F = F(t, \omega, y, z, \gamma)$ Hamiltonian
- $u = u(t, \omega) : [0, T] \times \Omega \rightarrow \mathbb{R}$ *non-anticipating*, i.e.,

$$u(t, \omega) = u(t, \omega_{\cdot \wedge t}) \quad \text{"="} \quad u(t, \{\omega_s\}_{s \leq t})$$

WARNING: Don't confuse PPDE with stochastic (or rough) PDE

$$u(t, x, \omega) = u_0 + \int_0^t F[\dots] ds + \int_0^t G[\dots] d\omega_s$$

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Intrinsic mathematical:

- Very few results available for PDEs on those (infinite-dimensional) path spaces
- In contrast: Large literature for PDEs on Hilbert space

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- Very few results available for PDEs on those (infinite-dimensional) path spaces
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Optimal control of delay equations and/or with path-dependent terminal cost:

$$\text{Minimize } J(t, \omega, a(\cdot)) := \sup_{s \leq t} |x^{t, \omega, a(\cdot)}(s)|$$

subject to $x = x^{t, \omega, a(\cdot)}$ solving

$$\begin{aligned}x'(s) &= f(x(s-1), a(s)) \text{ on } (t, T), \\x &= \omega \text{ on } [0, t].\end{aligned}$$

Formally, value function $v(t, \omega) := \inf_{a(\cdot)} J(t, \omega, a(\cdot))$ solves

$$-\partial_t v - \inf_a [f(\omega(s-1)) \partial_\omega v] = 0,$$

$$v(T, \omega) = \sup_{s \leq T} |\omega(s)|.$$

Pricing of path-dependent options in mathematical finance:

$$u(t, \omega) := \mathbb{E}_{t, \omega}[\xi],$$

where ξ is a functional of Brownian motion B , e.g.,

$$\xi(\tilde{\omega}) = \max \left\{ \sup_{s \leq t} |\omega(s)|, \sup_{t < s \leq T} |B(s, \tilde{\omega})| \right\} \text{ for } \mathbb{P}_{t, \omega}\text{-a.e. } \tilde{\omega}.$$

Formally, u solves

$$\begin{aligned} - \left[\partial_t u + \frac{1}{2} \partial_{\omega\omega}^2 u \right] &= 0, \\ u(T, \cdot) &= \xi. \end{aligned}$$

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$$\Omega = C([0, T], \mathbb{R}) \text{ from now on.}$$

Kim (since 1980s), Lukoyanov (since late 1990s).

Definition

$u : [0, T] \times \Omega \rightarrow \mathbb{R}$ is in $C^{1,1}$ if u is non-anticipating, continuous, and

\exists functions $\partial_t u, \partial_\omega u : [0, T] \times \Omega \rightarrow \mathbb{R}$ non-anticipating and continuous:

$\forall \omega \in AC([0, T]) : \forall s \leq t :$

$$u(t, \omega) - u(s, \omega) = \int_s^t [\partial_t u(r, \omega) + \partial_\omega u(r, \omega) \omega'(r)] dr.$$

Example: If f and g are smooth and

$$u(t, \omega) = f(t, \omega(t)) + \int_0^t g(s, \omega(s)) ds$$

then

$$\partial_t u(t, \omega) = \frac{\partial}{\partial t} f(t, \omega(t)) + g(t, \omega(t)), \quad \partial_\omega u(t, \omega) = \frac{\partial}{\partial x} f(t, \omega(t)).$$

Dupire (2009) and, in 2010s, Cont, Fournié, Ekren, K., Touzi, Zhang, etc.

Definition

$u : [0, T] \times \Omega \rightarrow \mathbb{R}$ is in $\mathcal{C}^{1,2}$ if u is non-anticipating, continuous, and

\exists functions $\partial_t u, \partial_\omega u, \partial_{\omega\omega}^2 u : [0, T] \times \Omega \rightarrow \mathbb{R}$ non-anticipating and continuous:

\forall Itô semimartingale X , i.e., $dX_t = b_t dt + \sigma_t dW_t: \forall s \leq t :$

$$u(t, X) - u(s, X) = \int_s^t \left[\partial_t u(r, X) + \partial_\omega u(r, X) b_r + \frac{1}{2} \partial_{\omega\omega}^2 u(r, X) \sigma_r^2 \right] dr \\ + \int_s^t [\partial_\omega(r, X) \sigma_r] dW_r$$

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Crandall–Lions (TAMS, 1983).

Definition

$u : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ continuous is a viscosity subsolution of

$$-\partial_t u(t, x) - \tilde{F}(t, \partial_x u(t, x)) = 0 \text{ at } (t, x),$$

if, for each test function $\varphi \in \underline{A}u(t, x)$,

$$-\partial_t \varphi(t, x) - \tilde{F}(t, \partial_x \varphi(t, x)) \leq 0.$$

The test function space is defined by

$$\underline{A}u(t, x) := \left\{ \varphi \in C^{1,2}([0, T] \times \mathbb{R}) : \right. \\ \left. 0 = (\varphi - u)(t, x) = \inf_{(s,y)} (\varphi - u)(s, y) \right\}$$

Lukoyanov (2007) and Bayraktar–K. (JFA, 2018).

Fix $L \geq 0$. Assume $|F(t, z) - F(t, \tilde{z})| \leq L|z - \tilde{z}|$.

Definition

$u : [0, T] \times \Omega \rightarrow \mathbb{R}$ non-anticipating, continuous is a viscosity L -subsolution of

$$-\partial_t u(t, \omega) - F(t, \partial_\omega u(t, \omega)) = 0 \text{ at } (t, \omega),$$

if, for each test function $\varphi \in \underline{\mathcal{A}}^L u(t, \omega)$,

$$-\partial_t \varphi(t, \omega) - F(t, \partial_\omega \varphi(t, \omega)) \leq 0.$$

The test function space is defined by

$$\underline{\mathcal{A}}^L u(t, \omega) := \left\{ \varphi \in C^{1,2} : 0 = (\varphi - u)(t, \omega) = \inf_{(s, X) \in [t, T] \times \mathcal{X}^L(t, \omega)} (\varphi - u)(s, X) \right\},$$

where the (compact) set $\mathcal{X}^L(t, \omega)$ is defined by

$$\mathcal{X}^L(t, \omega) := \{X \in \Omega : X|_{[0, t]} = \omega|_{[0, t]} \text{ and } X|_{[t, T]} \in AC([t, T]) \text{ with } \sup_{t \leq s \leq T} |X'(s)| \leq L\}.$$

Ekren–K.–Touzi–Zhang (AOP, 2014), Ekren–Touzi–Zhang (AOP, 2016ab), Ren–Rosestolato (SIMA, 2020), etc.

Fix $L \geq 0$. Assume $|F(t, z, \gamma) - F(t, \tilde{z}, \tilde{\gamma})| \leq L(|z - \tilde{z}| + |\gamma - \tilde{\gamma}|)$.

Definition

$u : [0, T] \times \Omega \rightarrow \mathbb{R}$ non-anticipating, continuous is a viscosity \mathcal{P}^L -subsolution of

$$-\partial_t u(t, \omega) - F(t, \partial_\omega u(t\omega), \partial_{\omega\omega}^2 u(t, \omega)) = 0 \text{ at } (t, \omega),$$

if, for each test function $\varphi \in \underline{\mathcal{A}}^{\mathcal{P}^L} u(t, \omega)$,

$$-\partial_t \varphi(t, \omega) - F(t, \partial_\omega u(t\omega), \partial_{\omega\omega}^2 \varphi(t, \omega)) \leq 0.$$

The test function space is defined by

$$\underline{\mathcal{A}}^{\mathcal{P}^L} u(t, \omega) := \left\{ \varphi \in \mathcal{C}^{1,2} : \right.$$

$$\left. 0 = (\varphi - u)(t, \omega) = \inf_{\tau \in \mathcal{T}^t} \inf_{\mathbb{P} \in \mathcal{P}^L(t, \omega)} \mathbb{E}^{\mathbb{P}} [(\varphi - u)(\tau, X)] \right\}.$$

The test function space is defined by

$$\underline{\mathcal{A}}^{\mathcal{P}^L} u(t, \omega) := \left\{ \varphi \in \mathcal{C}^{1,2} : \right. \\ \left. 0 = (\varphi - u)(t, \omega) = \inf_{\tau \in \mathcal{T}^t} \inf_{\mathbb{P} \in \mathcal{P}^L(t, \omega)} \mathbb{E}^{\mathbb{P}} [(\varphi - u)(\tau, X)] \right\},$$

where

- $\mathcal{T}^t = \{\text{all } [t, T]\text{-valued stopping times}\},$
- X canonical process on Ω , i.e., $X_t(\tilde{\omega}) = \tilde{\omega}(t),$
- and the $\mathcal{P}^L(t, \omega)$ is defined by

$$\mathcal{P}^L(t, \omega) := \left\{ \text{all probability measures } \mathbb{P} \text{ on } \Omega \text{ such that, } \mathbb{P}\text{-a.s.,} \right. \\ X|_{[0,t]} = \omega|_{[0,t]} \text{ and} \\ X|_{[t,T]} \text{ is an It\^o-semimartingale of the form} \\ dX_s = b_s ds + \sigma_s dW_s \\ \left. \text{with } \|b\|_{\infty} \leq L \text{ and } \|\sigma\|_{\infty} \leq \sqrt{2L}. \right\}$$